COGNITIVE ROBOTICS (10/07/2018)

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The exam will be graded IFF the following recommendations have been taken into account:

- Write clearly so that the teacher can easily understand your answers
- Write your name, surname, and student id on each sheet you deliver for evaluation
- For each exercise/question report clearly the number and sub-number (if present)
- You are not allowed to use any programmable device (e.g., smartphone, calculator, etc.)
- You can use pen or pencil, paper will be provided, you cannot use notes or books

Exercise 1 (Cognitive Architectures) [2+1+3+1]

Two main paradigms for the design of cognitive systems have been presented during classes, with hybrid approached, among the two resulting in being the most common ones. Answer the following:

- a) What is planning? Formalize a planning problem and its components.
- b) How planning could be use in a hybrid architecture including deliberative and reactive components?
- c) Using PPDL, define the planning problem of a sailor moving a wolf, a goat, and a cabbage across a river (you might need to use conditional effects in actions ...):
 - The boat is tiny and can only carry one passenger at a time
 - If the sailor leaves the wolf and the goat alone together, the wolf will eat the goat.
 - If the sailor leaves the goat and the cabbage alone together, the goat will eat the cabbage.
- *d*) Is the previous problem solvable using pure STRIPS definitions instead of ADL? Explain why.

Exercise 2 (ROS and friends) [4]

Describe and design a simple robot using ROS nodes and topics (what it does, which sensors uses, what information it exchange).

Exercise 3 (Human Robot Interaction) [2+2+2+2]

Design a desktop robotic lamp which interacts with a student preparing his/her Cognitive Robotics exam.

- a) Provide a sketch of the robot identifying actuators and relevant moving parts
- b) What kind of sensors/actuators might be needed to interact with the person? Describe where to put them and explain why!
- c) What kind of emotional interaction could it show/trigger? Why?
- d) What channels could be exploited to induce such an interaction?

Exercise 4 (Neural Networks) [2+2+2+2]

Let assume we want to train a feed forward neural network for classification:

- a) Provide a drawing for the network in the case of two classes, define the activation functions, and provide the overall computed function
- b) What error function is used for classification and why? Provide its derivation.
- c) How neural networks are trained? What are the possible issues of such a procedure and how they could be avoided?
- d) Can ReLu activation function be used for classification? Why?